

Fracton Phases of Matter

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Overview

1. Introduction
2. Why Fractons?
3. Fractons in gauge field
4. Conclusion

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These quasiparticles are referred to as "fractons."

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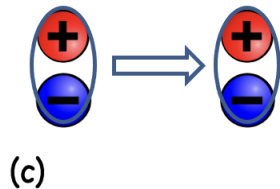
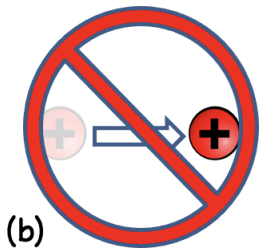
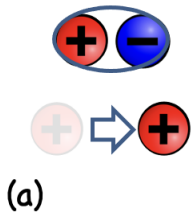
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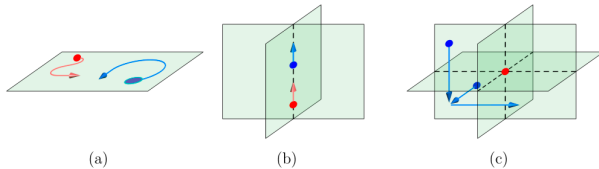
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- Fractons can occasionally move by forming specific bound states, such as dipoles. These mobile bound states typically exhibit mobility only in certain directions, giving rise to terms such as **lineon** and **planon**. [Pretko et al., 2020]

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4. Holography

Fractons in gauge field

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- From a mathematical perspective, fractons emerge as intriguing phenomena that can be described by tensor gauge theories. [\[Pretko, 2017a, Pretko, 2017b\]](#)

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Scalar charge theory:

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Scalar charge theory:

$$\begin{aligned}\{\hat{Q}, \hat{Q}_i\} &= \{\hat{Q}, \hat{P}_i\} = 0, & \{\hat{P}_i, \hat{Q}_j\} &= \delta_{ij} \hat{Q}, \\ \{\hat{P}_i, \hat{J}_{jk}\} &= \delta_{ik} \hat{P}_j - \delta_{ij} \hat{P}_k, & \{\hat{Q}_i, \hat{J}_{jk}\} &= \delta_{ik} \hat{Q}_j - \delta_{ij} \hat{Q}_k, \\ \{\hat{J}_{ij}, \hat{J}_{kl}\} &= \delta_{il} \hat{J}_{jk} - \delta_{ik} \hat{J}_{jl} + \delta_{jk} \hat{J}_{il} - \delta_{jl} \hat{J}_{ik},\end{aligned}\tag{2}$$

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Dipole Transformations

$$\delta_\beta \mathbf{x}_i = 0, \quad \delta_\beta \mathbf{p}_i = q\beta_i, \quad \delta_\beta \mathbf{E} = 0, \quad \delta_\beta t = 0\tag{3}$$

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Isolated fractons

$$S_{\text{Fracton}} = \int d\tau [-E\dot{t} + (\vec{p} - q\vec{\chi}) \cdot \dot{\vec{x}} - \frac{e}{2}(E^2 - \theta^2)], \quad (4)$$

The equations of motion for this type of particles are

$$\dot{t} = -eE, \quad \dot{\vec{x}} = 0, \quad \dot{E} = 0, \quad \dot{\vec{p}} = q\dot{\vec{\chi}} \quad (5)$$

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$$S_{\text{Dipole}} = \int d\tau [-E\dot{t} + \vec{p} \cdot \dot{\vec{x}} - \frac{e}{2}(E^2 - \theta^2) + d^i \dot{t} \partial_i A_0(\vec{x}, t) - \dot{x}^i d^j A_{ij}(\vec{x}, t)]. \quad (6)$$

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Consequently, we can express the equations of motion as follows:

$$\begin{aligned} \dot{t} &= -eE, \quad \dot{\vec{x}} = 0, \\ \dot{E} &= -d^i \partial_i \dot{A}_0 + d^i \dot{t} \partial_t \partial_i A_0 - \dot{x}^j d^i \partial_t A_{ij} = 0, \\ \dot{p}_m &= d^j \dot{A}_{mj} + d^i \dot{t} \partial_i \partial_m A_0(\vec{x}, t) - \dot{x}^i d^j \partial_m A_{ij} \\ &= d^j \partial_t A_{mj} + d^j \partial_j \partial_m A_0 = d^j E_{mj}. \end{aligned} \quad (7)$$

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1- The first mobile dipole:

The first mobile dipole

$$S_{\text{Dipole}} = \int d\tau \left[-E\dot{t} + \vec{p} \cdot \dot{\vec{x}} - \frac{e}{2}(p^2 - \epsilon^2) + \vec{\chi} \cdot (\vec{d} - \vec{\psi}) + d^i \dot{t} \partial_i A_0(\vec{x}, t) - \dot{x}^i d^j A_{ij}(\vec{x}, t) \right]. \quad (8)$$

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The resulting equations of motion are:

$$\begin{aligned} \dot{t} &= 0, \quad \dot{\vec{x}} = e\vec{p}, \\ \dot{E} &= -2d^i \dot{x}^j E_{ij}, \quad \dot{p}_m = d^j \dot{x}^i (\partial_i A_{mj} - \partial_m A_{ij}) = d^j (\epsilon_{ijl} \dot{x}^i B_m^l). \end{aligned} \quad (9)$$

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$$S_{\text{Dipole}} = \int d\tau [-E\dot{t} + \vec{p} \cdot \dot{\vec{x}} - \frac{e}{2}(p^2 - \epsilon^2) - \frac{\tilde{e}}{2}(E^2 - \theta^2) + \vec{\chi} \cdot (\vec{d} - \vec{\psi}) + d^i \dot{t} \partial_i A_0(\vec{x}, t) - \dot{x}^i d^j A_{ij}(\vec{x}, t)]. \quad (10)$$

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The resulting equations of motion are:

$$\begin{aligned} \dot{t} &= -\tilde{e}E, \quad \dot{\vec{x}} = e\vec{p}, \quad \dot{E} = -2d^i \dot{x}^j E_{ij}, \\ \dot{p}_m &= d^j [(\dot{t} \partial_t A_{mj} + \dot{x}^i \partial_i A_{mj}) + \dot{t} \partial_i \partial_m A_0(\vec{x}, t) - \dot{x}^i d^j \partial_m A_{ij}] = d^j (E_{mj} + \epsilon_{ijl} \dot{x}^i B_m^l). \end{aligned} \quad (11)$$

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 4. Geometric manifestations

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Thank You

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